State-of-the-art detector controller for ESO instruments

Leander H. Mehrghan, Domingo Alvarez, Dietrich Baade, Claudio Cumani, Siegfried Eschbaumer, Gert Finger, Christoph Geimer, Manfred Meyer, Javier Reyes, Jörg Stegmeier, Mirko Todorovic

European Organization for Astronomical Research in the Southern Hemisphere

Introduction

The ESO NGC, a New General common Controller, had its first light at the ESO Paranal Observatory in 2012. The controller has evolved over three decades from previous controller generations, namely the ESO IRACE and FIERA detector controllers. NGC is a controller platform which can be adapted and customized for all infrared and optical detectors. Recently NGC has also been deployed in adaptive optics with electron multiplication CCDs and infrared electron avalanche photodiode arrays. Since NGC runs all new detector systems of ESO instruments, a uniform platform is available at the observatory which facilitates operation and maintenance.

NGC structure

The NGC controller is based on the Xilinx FPGA. In comparison to the previous ESO controllers, all digital parts, like RAMs, FIFOs, and the sequencer, are fully implemented in the FPGA, so that less external components are needed. The detector front-end electronics are connected via fiber optic cables to the PCIe card of the PC. Over the same cable commands and data are transferred in a time multiplexing technique.

Development

The NGC architecture is highly adaptable and flexible. Implementation and integration of new technology standards or well developed and optimized industrial components like ADCs/DACs or PCI-express can be done in a relatively short time. Since the NGC team is also directly involved in detector evaluation and components like ADCs or DACs or PCI-express can be standards or well developed and optimized industrial parts, like RAMs, FIFOs, and sequencers, are fully implemented in the FPGA, so that less external components are needed. The detector front-end electronics are connected via fiber optic cables to the PCIe card of the PC. Over the same cable commands and data are transferred in a time multiplexing technique.

PCI-express

The NGC hardware is controlled through a PCI-Express interface board providing up to 4 command channels and 4 multiplexed DMA-channels delivering the data through a sustained scatter-gather DMA engine (circular buffer). Currently the implemented hardware is a commercial off-the-shelf device called HTG, which has been adapted to the NGC. With the two fiber interfaces we can independently and simultaneously control and readout two different AO camera heads or two NGC front-ends. In addition there is a fiber interface with SPARTA protocol to SPARTA system. We are going to build our own PCI Express hardware, because it will be more compact and will have five fiber optic interfaces, instead of two. With this we were able to use one PCI-Express and one PCIe to readout all 24 CCDs of the MUSE instrument.

Adaptability and modularity

The NGC controller is a modular, customizable system. Just like Lego blocks we can combine different modules to cover our needs. The FEB module (front-end basic module) generates 16 clocks and 20 biases and also has 4 full differential video channels. The AO module has 32 differential video channels, of which exists three different versions with different pixel speeds (1, 3, 10 MHz), but all are plug and play compatible. As an example the MUSE instrument uses four AO camera heads or two NGC front-ends. In addition there is a fiber interface with SPARTA protocol to SPARTA system. We are going to build our own PCI Express hardware, because it will be more compact and will have five fiber optic interfaces, instead of two. With this we were able to use one PCI-Express and one PCIe to readout all 24 CCDs of the MUSE instrument.

NGC-software

The NGC software comprises the DMA and communication-port device driver, high-throughput data acquisition and pre-processing facilities and the full exposure control for scientific operations. The software can be operated as command/database driven or for stand-alone mode, through a graphical user interface. The data can be visualized in real-time on a quick-look display application. The NGC-software includes configuration packages and pixel-processing algorithms for all ESO standard detectors employed for infrared, mid-infrared, optical and adaptive optics systems. The software runs on both 32-bit and 64-bit Linux platforms (kernel version 2.6.3). Hard real-time applications can make use of the low-latency DMA device driver developed for the Virtuoso RTOS running on the MicroE/500 PowerPC architecture.

Applications using the NGC

The NGC already had its first light at the VLT Telescope in Chile. Various ESO instruments already use the NGC. An instrument like MUSE reads out 24 CCDs simultaneously and SPHERE uses several different types of detectors like the Hawaii2RG and the Hawaii1 infrared detectors, ZIMPOL CCD and adaptive optics CCD220. Recently we achieved the best performance with the SAPHIRA MOV pXPID detector. The ESPRESSO instrument, with largest capacitance ever handled by a controller, had its first light with the NGC.

Different type of NGCs

Up-to-now the scientific NGC (SCI-NGC) covered our needs for all infrared and optical detectors. It is in use for readout of high speed eAPD infrared, mid-IR detectors, as well low noise CCDs. But in the area of adaptive optics to readout e2v CCD220 detector we required a compact, high speed controller. Our solution is a very compact and therefore hardware wise different solution which is called adaptive optics NGC (AO-NGC). We use the same back-end interface for both NGC types. Also the firmware can be mostly taken and adapted to the new need. However there is no single active component on the AO-NGC front-end which is used on SCI-NGC and vice versa. With the SCI-NGC and AO-NGC combinations, ESO is able to readout any type of detector.

Fanless housing

Due to the requirement for NGC use in the VLT Interferometer delay tunnel for the next generation of ESO instruments, we needed to implement a NGC which is vibration-free and silent. Hence the Thermacore company were contracted to design a fanless water cooled housing. The final solution is now operational and works very well. The heat from the boards is transferred away by inserting them into conduction frames which are thermally interlocked with the cold inner housing. Thermal foam boards have been used for a neat electrical connection of the boards to the frames. Special wedge locks allow the best thermal connection between the conduction frames and the cold wall.

Future development

Besides the usual ongoing developments we are also developing a controller prototype to readout the high order wavefront sensor currently being developed for the ELT. For this it is required to read 22 LVDS outputs at 200 MHz in a real time control loop. The firmware is an adaptation of the SCI-NGC and therefore the same control software can be used.

Upgrading the FPGA to a more powerful version with much more integrated logic cells, like the Xilinx Virtuoso, will give us more freedom and efficiency for on-board pre-processing.