NI Vision

NI PXI/PCI-1422 User Manual
High-Quality Image Acquisition Device
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Class A
Federal Communications Commission
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Canadian Department of Communications
This Class A digital apparatus meets all requirements of the Canadian Interference-Causing Equipment Regulations. Cet appareil numérique de la classe A respecte toutes les exigences du Règlement sur le matériel brouilleur du Canada.

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* The CE marking Declaration of Conformity contains important supplementary information and instructions for the user or installer.
Conventions

The following conventions are used in this manual:

<> Angle brackets that contain numbers separated by an ellipsis represent a range of values associated with a bit or signal name—for example, AO <3..0>.

» The » symbol leads you through nested menu items and dialog box options to a final action. The sequence File » Page Setup » Options directs you to pull down the File menu, select the Page Setup item, and select Options from the last dialog box.

This icon denotes a note, which alerts you to important information.

This icon denotes a caution, which advises you of precautions to take to avoid injury, data loss, or a system crash.

When symbol is marked on a product, it denotes a warning advising you to take precautions to avoid electrical shock.

italic Italic text denotes variables, emphasis, a cross-reference, or an introduction to a key concept. Italic text also denotes text that is a placeholder for a word or value that you must supply.

monospace Text in this font denotes text or characters that you should enter from the keyboard, sections of code, programming examples, and syntax examples. This font is also used for the proper names of disk drives, paths, directories, programs, subprograms, subroutines, device names, functions, operations, variables, filenames, and extensions.
# Contents

## Chapter 1
**Introduction**
- About the NI 1422 ................................................................. 1-1
- Using PXI with CompactPCI .................................................. 1-2
- Software Overview ................................................................. 1-3
  - NI-IMAQ Driver Software .................................................. 1-3
  - National Instruments Application Software ..................... 1-4
    - Vision Builder for Automated Inspection ..................... 1-4
    - Vision Development Module ..................................... 1-4
  - Integration with DAQ and Motion Control ..................... 1-5

## Chapter 2
**Hardware Overview**
- Functional Overview ............................................................ 2-1
  - Differential/TTL Level Converters .................................. 2-2
  - LUTs .................................................................................. 2-2
  - Multiple-Tap Data Formatter .......................................... 2-3
  - SDRAM ............................................................................. 2-3
  - Advanced Clock Generation ........................................... 2-3
  - RS-232 Serial Interface (UART) ....................................... 2-3
  - Trigger Control and Mapping Circuitry ......................... 2-3
  - High-Speed Timing ........................................................... 2-4
  - Acquisition, Scaling, ROI .................................................. 2-4
  - Scatter-Gather DMA Controllers .................................... 2-4
  - Bus Master PCI Interface .................................................. 2-4
  - Board Configuration NVRAM ............................................ 2-4
  - Video Acquisition ............................................................. 2-5
  - Start Conditions ................................................................. 2-5
  - Acquisition Window Control .......................................... 2-5

## Chapter 3
**Signal Connections**
- I/O Connector ........................................................................ 3-1
- Signal Descriptions ............................................................... 3-3
Appendix A
Technical Support and Professional Services

Glossary

Index
Introduction

This chapter describes the NI PXI/PCI-1422 (NI 1422) image acquisition device and your software programming choices.

About the NI 1422

The NI 1422 is an image acquisition device for PXI, PCI, and CompactPCI chassis that supports a diverse range of digital cameras from several different camera companies. The NI 1422 acquires digital images in real time and can store the images in onboard frame memory or transfer them directly to system memory. The device can capture up to 16 bits of data at a time at clock speeds up to 40 MHz.

The NI 1422 is simple to configure and is factory calibrated so that you can easily install the device and begin acquiring images. The NI 1422 ships with NI Vision Acquisition Software, which includes NI-IMAQ, the National Instruments driver software you can use to directly control the NI 1422 and other National Instruments image acquisition devices. Using NI-IMAQ, you can quickly and easily start your applications without having to program the device at the register level.

Featuring a high-speed data flow path, the NI 1422 is ideal for both industrial and scientific environments. As a stand-alone device, the NI 1422 supports up to 16 bits of differential video data, four general-purpose control lines that can be configured to generate precise timing signals to control digital camera acquisition, and four external input/output (I/O) lines that you can use as triggers or as high-speed digital I/O lines. If you require more advanced triggering or digital I/O lines (either digital or analog), you can use the NI 1422 and NI-IMAQ with the National Instruments Data Acquisition (DAQ) product line.

A common problem with other image acquisition devices is that you cannot easily synchronize several functions to a common trigger or timing event. The NI 1422 uses its Real-Time System Integration (RTSI) bus to solve this problem. The RTSI bus consists of the National Instruments RTSI bus interface and ribbon cable to route additional timing and trigger signals between the NI 1422 and up to four National Instruments DAQ or image acquisition devices.
acquisition devices in your computer. The RTSI bus can even synchronize multiple image acquisition hardware captures.

For detailed specifications of the NI 1422, refer to the Specifications section of Getting Started with the NI PXI/PCI-1422.

Using PXI with CompactPCI

Using PXI-compatible products with standard CompactPCI products is an important feature provided by the PXI Specification, Revision 1.0. If you use a PXI-compatible plug-in device in a standard CompactPCI chassis, you will be unable to use PXI-specific functions, but you can still use the basic plug-in device functions. For example, the RTSI bus on the NI PXI-1422 device is available in a PXI chassis, but not in a CompactPCI chassis.

The CompactPCI specification permits vendors to develop sub-buses that coexist with the basic PCI interface on the CompactPCI bus. Compatible operation is not guaranteed between CompactPCI devices with different sub-buses or between CompactPCI devices with sub-buses and PXI. The standard implementation for CompactPCI does not include these sub-buses. The NI PXI-1422 device works in any standard CompactPCI chassis adhering to the PICMG 2.0 R2.1 CompactPCI core specification using the 64-bit definition for J2.

PXI-specific features are implemented on the J2 connector of the CompactPCI bus. Table 1-1 lists the J2 pins the NI PXI-1422 device uses. The PXI device is compatible with any CompactPCI chassis with a sub-bus that does not drive these lines. Even if the sub-bus is capable of driving these lines, the PXI device is still compatible as long as those pins on the sub-bus are disabled by default and are never enabled. Damage may result if these lines are driven by the sub-bus.

<table>
<thead>
<tr>
<th>PXI-1422 Signal</th>
<th>PXI Pin Name</th>
<th>PXI J2 Pin Number</th>
</tr>
</thead>
<tbody>
<tr>
<td>RTSI Trigger &lt;0..6&gt;</td>
<td>PXI Trigger &lt;0..6&gt;</td>
<td>B16, A16, A17, A18, B18, C18, E18</td>
</tr>
</tbody>
</table>
Software Overview

Programming the NI 1422 requires the NI-IMAQ driver software for controlling the hardware. National Instruments also offers the following application software packages for analyzing and processing your acquired images.

- **Vision Builder for Automated Inspection (AI)**—Allows you to configure solutions to common inspection tasks.
- **National Instruments Vision Development Module**—Provides customized control over hardware and algorithms.

The following sections provide an overview of the driver software and the application software. For detailed information about individual software packages, refer to the documentation specific to each package.

**NI-IMAQ Driver Software**

The NI 1422 ships with NI Vision Acquisition Software, which includes the NI-IMAQ driver software. NI-IMAQ has an extensive library of functions—such as routines for video configuration, continuous and single shot image acquisition, memory buffer allocation, trigger control, and device configuration—you can call from the application development environment (ADE). NI-IMAQ handles many of the complex issues between the computer and the image acquisition device, such as programming interrupts and camera control.

NI-IMAQ performs all functions required for acquiring and saving images but does not perform image analysis. For image analysis functionality, refer to the **National Instruments Application Software** section of this chapter.

NI-IMAQ also provides the interface path between the NI 1422 and LabVIEW, LabWindows™/CVI™, or a text-based programming environment. The NI-IMAQ software kit includes a series of libraries for image acquisition for LabVIEW, LabWindows/CVI, and Measurement Studio, which contains libraries for Microsoft Visual Basic.

NI-IMAQ features both high-level and low-level functions. Examples of high-level functions include the sequences to acquire images in multi-buffer, single-shot, or continuous mode. An example of a low-level function is configuring an image sequence, since it requires advanced understanding of the image acquisition device and image acquisition principles.
National Instruments Application Software

This section describes the National Instruments application software packages you can use to analyze and process the images you acquire with the NI 1422.

Vision Builder for Automated Inspection

NI Vision Builder for Automated Inspection (AI) is configurable machine vision software that you can use to prototype, benchmark, and deploy applications. Vision Builder AI does not require programming, but is scalable to powerful programming environments.

Vision Builder AI allows you to easily configure and benchmark a sequence of visual inspection steps, as well as deploy the visual inspection system for automated inspection. With Vision Builder AI, you can perform powerful visual inspection tasks and make decisions based on the results of individual tasks. You also can migrate the configured inspection to LabVIEW, extending the capabilities of the applications if necessary.

Vision Development Module

The Vision Development Module is an image acquisition, processing, and analysis library of more than 270 functions for the following common machine vision tasks:

- Pattern matching
- Particle analysis
- Gauging
- Taking measurements
- Grayscale, color, and binary image display

You can use the Vision Development Module functions individually or in combination. With the Vision Development Module, you can acquire, display, and store images, as well as perform image analysis, and processing. Using the Vision Development Module, imaging novices and experts can program the most basic or complicated image applications without knowledge of particular algorithm implementations.

As a part of the Vision Development Module, NI Vision Assistant is an interactive prototyping tool for machine vision and scientific imaging developers. With Vision Assistant, you can prototype vision applications quickly and test how various vision image processing functions work.
Vision Assistant generates a Builder file, which is a text description containing a recipe of the machine vision and image processing functions. This Builder file provides a guide you can use for developing applications in any ADE, such as LabWindows/CVI or Visual Basic, using the Vision Assistant machine vision and image processing libraries. Using the LabVIEW VI creation wizard, Vision Assistant can create LabVIEW VI block diagrams that perform the prototype you created in Vision Assistant. You then can use LabVIEW to add functionality to the generated VI.

Integration with DAQ and Motion Control

Platforms that support NI-IMAQ also support NI-DAQ and a variety of National Instruments DAQ devices. This allows integration between image acquisition devices and National Instruments DAQ products.

Use National Instruments high-performance stepper and servo motion control products with pattern matching software in inspection and guidance applications, such as locating alignment markers on semiconductor wafers, guiding robotic arms, inspecting the quality of manufactured parts, and locating cells.
Hardware Overview

This chapter presents an overview of the hardware functions on the NI 1422 and explains the operation of each functional unit making up the NI 1422.

Functional Overview

The NI 1422 features a flexible, high-speed data path optimized for the reception and formatting of video data from digital cameras.
The block diagram in Figure 2-1 illustrates the key functional components of the NI 1422.

**Figure 2-1.** NI 1422 Block Diagram

**Differential/TTL Level Converters**

The NI 1422 can drive and receive either TTL or differential-level camera control signals. These signal levels can be controlled independently for the control and enable lines on the 100-pin SCSI-type connector.

**LUTs**

The NI 1422 uses a 64 KB-by-16 bit lookup table (LUT) that you can use for two 256 B-by-8 bit LUT operations or one 64 KB-by-16 bit lookup table. You can configure this LUT to perform simple imaging operations such as contrast enhancement, data inversion, gamma manipulation, or other nonlinear transfer functions.
Multiple-Tap Data Formatter

Many digital cameras transfer multiple channels, or taps, of data simultaneously to increase the frame rate of the camera. However, the data in each tap may not be transferred in the traditional top-left to bottom-right direction. Also, the taps may not transfer data in similar directions.

The multiple-tap data formatting circuitry on the NI 1422 can reorder the data from up to two 8-bit taps. The data from each tap can be independently scanned either from left-to-right or right-to-left and top-to-bottom or bottom-to-top.

SDRAM

The NI 1422 comes with 32 MB of onboard high-speed synchronous dynamic RAM (SDRAM).

Advanced Clock Generation

The advanced clock generation circuitry on the NI 1422 generates frequencies from 500 kHz to 40 MHz for digital cameras that require an external clock.

RS-232 Serial Interface (UART)

You can use the RS-232 serial interface on the 100-pin SCSI-type connector to control digital cameras that also have a serial interface for camera control and configuration.

Note The RS-232 serial interface is accessible only via the NI-IMAQ driver software.

Trigger Control and Mapping Circuitry

The trigger control and mapping circuitry routes, monitors, and drives the external and RTSI bus trigger lines. You can configure each of these lines to start an acquisition on a rising or falling edge. In addition, you can drive each line asserted or unasserted, similar to a digital I/O line. You can also map pulses from the high-speed timing circuitry or many of the NI 1422 status signals to these trigger lines. There are four external and four RTSI bus triggers. You can program each of these triggers in polarity and direction.
High-Speed Timing

The high-speed timing circuitry on the NI 1422, built from high-speed counters, allows you to specify or generate precise, real-time control signals. You can map the output of this circuitry to a trigger line to provide accurate pulses and pulse trains.

Acquisition, Scaling, ROI

The acquisition, scaling, and region-of-interest (ROI) circuitry monitors the incoming video signals and routes the active pixels to the multiple-tap data formatter and SDRAM memory. The NI 1422 can perform ROI and scaling on all video lines and frames. Pixel and line scaling transfers certain multiples (two, four, or eight) of pixels and lines to onboard memory. In an ROI acquisition, you select an area within the acquisition window to transfer to the PCI bus.

Scatter-Gather DMA Controllers

The NI 1422 uses three independent onboard direct memory access (DMA) controllers. The DMA controllers transfer data between the onboard SDRAM memory buffers and the PCI bus. Each of these controllers supports scatter-gather DMA, which allows the DMA controller to reconfigure on-the-fly. Thus, the NI 1422 can perform continuous image transfers directly to either contiguous or fragmented memory buffers.

Bus Master PCI Interface

The NI 1422 implements the PCI interface with a National Instruments custom application-specific integrated circuit (ASIC), the PCI MITE. The PCI interface can transfer data at a maximum rate of 132 Mbytes/s in bus master mode. The NI 1422 can generate 8-, 16-, and 32-bit memory read and write cycles, both single and multiple. In slave mode, the NI 1422 is a medium-speed decoder that accepts both memory and configuration cycles. The interface logic ensures that the NI 1422 can meet PCI loading, driving, and timing requirements.

Board Configuration NVRAM

The NI 1422 contains onboard nonvolatile RAM (NVRAM) that configures all registers on power-up.
**Video Acquisition**

The NI 1422 can acquire digital video in a variety of modes and store the images in the onboard SDRAM memory or transfer the images directly to PCI system memory.

**Start Conditions**

The NI 1422 can start acquisitions in a variety of conditions:

- **Software control**—The NI 1422 supports software control of acquisition start. You can configure the NI 1422 to capture a fixed number of fields or frames. This configuration is useful for capturing a single frame or a sequence of frames.

- **Trigger control**—You can start an acquisition by enabling external or RTSI bus trigger lines. Each of these 11 inputs can start a video acquisition on a rising or falling edge. You can use all four external triggers and up to four RTSI bus triggers simultaneously.

- **Delayed acquisition**—You can use either software or triggers to start acquisitions instantaneously or after skipping a specific number of images.

- **Frame/field selection**—With an interlaced camera and the NI 1422 in frame mode, you can program the NI 1422 to start an acquisition on any odd or even field.

**Acquisition Window Control**

You can configure numerous parameters on the NI 1422 to control the video acquisition window. A brief description of each parameter follows:

- **Acquisition window**—The NI 1422 allows the user to specify a particular region of active pixels and active lines within the incoming video data. The active pixel region selects the starting pixel and number of pixels to be acquired relative to the assertion edge of the horizontal (or line) enable signal from the camera. The active line region selects the starting line and number of lines to be acquired relative to the assertion edge of the vertical (or frame) enable signal.

- **Region of interest**—The NI 1422 uses a second level of active pixel and active line regions for selecting a region of interest. Using the region-of-interest circuitry, the board acquires only a selected subset of the acquisition window.
• **Scaling down**—The scaling-down circuitry also controls the active acquisition region. The NI 1422 can scale down a frame by reducing the number of pixels per line, the number of lines per frame, or both. For active pixel selection, the NI 1422 can select every pixel, every other pixel, every fourth pixel, or every eighth pixel. For active line selection, the NI 1422 can select every line, every other line, every fourth line, or every eighth line. You can use the scaling-down circuitry in conjunction with the region-of-interest circuitry.

• **Interlaced video**—The NI 1422 supports both interlaced and noninterlaced digital video signals. In interlaced mode, the NI 1422 combines the odd and even fields into one contiguous frame for analysis. In noninterlaced mode, each field is treated as an independent frame.
This chapter describes signal connections for the NI 1422.

I/O Connector

The NI 1422 100-pin SCSI-type connector connects to all digital video data inputs, digital enable inputs, camera control outputs, RS-232 serial interface, and the external trigger signals. To access these connections, you can build your own custom cable or use one of the optional cables from National Instruments.

Note  Refer to the National Instruments Web site, ni.com/vision, for the latest information on optional cables and the cameras they support.
Figure 3-1 shows the pinout of the 100-pin SCSI-type connector.

<table>
<thead>
<tr>
<th>Pin</th>
<th>Description</th>
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<tbody>
<tr>
<td>1</td>
<td>Data0+</td>
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<tr>
<td>2</td>
<td>Data0-</td>
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<tr>
<td>3</td>
<td>Data1+</td>
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<td>44</td>
<td>EnableB-</td>
</tr>
<tr>
<td>45</td>
<td>EnableC+</td>
</tr>
<tr>
<td>46</td>
<td>EnableC-</td>
</tr>
<tr>
<td>47</td>
<td>EnableD+</td>
</tr>
<tr>
<td>48</td>
<td>EnableD-</td>
</tr>
<tr>
<td>49</td>
<td>Pixel Clock +</td>
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<td>50</td>
<td>Pixel Clock -</td>
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<td>82</td>
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<tr>
<td>83</td>
<td>RI (RS-232)</td>
</tr>
<tr>
<td>84</td>
<td>DTR (RS-232)</td>
</tr>
<tr>
<td>85</td>
<td>DSR (RS-232)</td>
</tr>
<tr>
<td>86</td>
<td>RTS (RS-232)</td>
</tr>
<tr>
<td>87</td>
<td>CTS (RS-232)</td>
</tr>
<tr>
<td>88</td>
<td>DCD (RS-232)</td>
</tr>
<tr>
<td>89</td>
<td>Master Clock1–</td>
</tr>
<tr>
<td>90</td>
<td>Master Clock1+</td>
</tr>
<tr>
<td>91</td>
<td>Master Clock0–</td>
</tr>
<tr>
<td>92</td>
<td>Master Clock0+</td>
</tr>
<tr>
<td>93</td>
<td>SOUT (RS-232)</td>
</tr>
<tr>
<td>94</td>
<td>SIN (RS-232)</td>
</tr>
<tr>
<td>95</td>
<td>External Trigger0</td>
</tr>
<tr>
<td>96</td>
<td>External Trigger1</td>
</tr>
<tr>
<td>97</td>
<td>External Trigger2</td>
</tr>
<tr>
<td>98</td>
<td>External Trigger3</td>
</tr>
</tbody>
</table>

**Figure 3-1.** NI 1422 Pin Assignments
Table 3-1 describes each signal connection on the 100-pin SCSI-type connector.

**Table 3-1. I/O Connector Signals**

<table>
<thead>
<tr>
<th>Signal Name</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Control&lt;0..3&gt;±</td>
<td>You can use the control lines on the NI 1422 to control digital camera features and timing information. Either static or dynamic, TTL or differential, signals can be generated on these lines to perform such functions as generating integration or shutter pulses to the digital cameras.</td>
</tr>
<tr>
<td>CTS</td>
<td>Clear to Send is used for RS-232 connections.</td>
</tr>
<tr>
<td>Data&lt;0..15&gt;±</td>
<td>Data&lt;0..15&gt;± allows you to connect data up to 16 bits wide in differential format to the NI 1422.</td>
</tr>
<tr>
<td>DCD</td>
<td>Data Carrier Detect is used for RS-232 connections.</td>
</tr>
<tr>
<td>DSR</td>
<td>Data Set Ready is used for RS-232 connections.</td>
</tr>
<tr>
<td>DTR</td>
<td>Data Terminal Ready is used for RS-232 connections.</td>
</tr>
<tr>
<td>Enable&lt;A..D&gt;±</td>
<td>The NI 1422 can receive any combination of up to four enable signals. These signals can be either TTL or differential. Examples of camera signals which might be connected to these pins are frame enable, line enable, even enable and odd enable. If your camera has a separate field signal, that line should be connected to Enable C.</td>
</tr>
<tr>
<td>External Trigger&lt;0..3&gt;</td>
<td>External Trigger&lt;0..3&gt; are TTL I/O lines used to start an acquisition or output to control external events. You can program the triggers to be rising-edge or falling-edge sensitive. You can also program the triggers to be programmatically asserted or unasserted similar to the function of a digital I/O line or to contain internal status signals (by using the onboard events) or specific pulse widths.</td>
</tr>
<tr>
<td>GND</td>
<td>GND is a direct connection to digital ground on the NI 1422.</td>
</tr>
<tr>
<td>Master Clock&lt;0..1&gt;±</td>
<td>You can use these two sets of pins to generate a master clock signal for your digital camera. Possible clock frequencies range from 500 kHz to 40 MHz.</td>
</tr>
<tr>
<td>Pixel Clock±</td>
<td>The NI 1422 uses the Pixel Clock input as a reference clock to latch the incoming video data.</td>
</tr>
<tr>
<td>RI</td>
<td>Ring Indicator is used for RS-232 connections.</td>
</tr>
</tbody>
</table>
## Table 3-1. I/O Connector Signals (Continued)

<table>
<thead>
<tr>
<th>Signal Name</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>RTS</td>
<td>Request to Send is used for RS-232 connections.</td>
</tr>
<tr>
<td>SIN</td>
<td>Serial Data In is used for RS-232 connections.</td>
</tr>
<tr>
<td>SOUT</td>
<td>Serial Data Out is used for RS-232 connections.</td>
</tr>
</tbody>
</table>
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  - **Self-Help Resources**—For answers and solutions, visit the award-winning National Instruments Web site for software drivers and updates, a searchable KnowledgeBase, product manuals, step-by-step troubleshooting wizards, thousands of example programs, tutorials, application notes, instrument drivers, and so on.
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## Glossary

<table>
<thead>
<tr>
<th>Symbol</th>
<th>Prefix</th>
<th>Value</th>
</tr>
</thead>
<tbody>
<tr>
<td>p</td>
<td>pico</td>
<td>$10^{-12}$</td>
</tr>
<tr>
<td>n</td>
<td>nano</td>
<td>$10^{-9}$</td>
</tr>
<tr>
<td>μ</td>
<td>micro</td>
<td>$10^{-6}$</td>
</tr>
<tr>
<td>m</td>
<td>milli</td>
<td>$10^{-3}$</td>
</tr>
<tr>
<td>k</td>
<td>kilo</td>
<td>$10^3$</td>
</tr>
<tr>
<td>M</td>
<td>mega</td>
<td>$10^6$</td>
</tr>
<tr>
<td>G</td>
<td>giga</td>
<td>$10^9$</td>
</tr>
<tr>
<td>T</td>
<td>tera</td>
<td>$10^{12}$</td>
</tr>
</tbody>
</table>

### Symbols

- **%**: Percent.
- **+**: Positive of, or plus.
- **/**: Per.
- **Ω**: Ohm.
- **±**: Plus or minus.
- **–**: Negative of, or minus.

### A

- **A**: Amperes.
- **AC**: Alternating current.
- **acquisition window**: The image size specific to a video standard or camera resolution.
active line region  The region of lines actively being stored. Defined by a line start (relative to the vertical synchronization signal) and a line count.

active pixel region  The region of pixels actively being stored. Defined by a pixel start (relative to the horizontal synchronization signal) and a pixel count.

address  Value that identifies a specific location (or series of locations) in memory.

ANSI  American National Standards Institute.

API  Application programming interface.

area  A rectangular portion of an acquisition window or frame that is controlled and defined by software.

array  Ordered, indexed set of data elements of the same type.

ASIC  Application-Specific Integrated Circuit. A proprietary semiconductor component designed and manufactured to perform a set of specific functions for specific customer needs.

B

b  Bit. One binary digit, either 0 or 1.

B  Byte. Eight related bits of data, an eight-bit binary number; also used to denote the amount of memory required to store one byte of data.

buffer  Temporary storage for acquired data.

bus  A group of conductors that interconnect individual circuitry in a computer, such as the PCI bus; typically the expansion vehicle to which I/O or other devices are connected.

C

C  Celsius.

cache  High-speed processor memory that buffers commonly used instructions or data to increase processing throughput.

CMOS  Complementary metal-oxide semiconductor.
<table>
<thead>
<tr>
<th>Term</th>
<th>Definition</th>
</tr>
</thead>
<tbody>
<tr>
<td>Compact PCI</td>
<td>Refers to the core specification defined by the PCI Industrial Computer Manufacturer’s Group (PICMG).</td>
</tr>
<tr>
<td>conversion device</td>
<td>Device that transforms a signal from one form to another. For example, analog-to-digital converters (ADCs) for analog input and digital-to-analog converters (DACs) for analog output.</td>
</tr>
<tr>
<td>CPU</td>
<td>Central processing unit.</td>
</tr>
<tr>
<td>DAQ</td>
<td>Data acquisition. (1) Collecting and measuring electrical signals from sensors, transducers, and test probes or fixtures and inputting them to a computer for processing. (2) Collecting and measuring the same kinds of electrical signals with A/D or DIO boards plugged into a computer, and possibly generating control signals with D/A and/or DIO boards in the same computer.</td>
</tr>
<tr>
<td>dB</td>
<td>Decibel. The unit for expressing a logarithmic measure of the ratio of two signal levels: $\text{dB} = 20\log_{10} \frac{V_1}{V_2}$, for signals in volts.</td>
</tr>
<tr>
<td>DC</td>
<td>Direct current.</td>
</tr>
<tr>
<td>default setting</td>
<td>A default parameter value recorded in the driver; in many cases, the default input of a control is a certain value (often 0) that means <em>use the current default setting</em>.</td>
</tr>
<tr>
<td>DIN</td>
<td>Deutsche Industrie Norme. A format for electrical connectors.</td>
</tr>
<tr>
<td>DMA</td>
<td>Direct memory access. A method by which data can be transferred to and from computer memory from and to a device or memory on the bus while the processor does something else; DMA is the fastest method of transferring data to/from computer memory.</td>
</tr>
<tr>
<td>DRAM</td>
<td>Dynamic RAM.</td>
</tr>
<tr>
<td>drivers</td>
<td>Software that controls a specific hardware device, such as an image acquisition board.</td>
</tr>
<tr>
<td>dynamic range</td>
<td>The ratio of the largest signal level a circuit can handle to the smallest signal level it can handle (usually taken to be the noise level), normally expressed in decibels.</td>
</tr>
</tbody>
</table>
### Glossary

#### E

**EEPROM**
Electrically erasable programmable read-only memory. ROM that can be erased with an electrical signal and reprogrammed.

**external trigger**
A voltage pulse from an external source that triggers an event such as A/D conversion.

#### F

**field**
For an interlaced video signal, a field is half the number of horizontal lines needed to represent a frame of video. The first field of a frame contains all the odd-numbered lines, the second field contains all of the even-numbered lines.

**FIFO**
First-in first-out memory buffer. The first data stored is the first data sent to the acceptor; FIFOs are used on image acquisition devices to temporarily store incoming data until that data can be retrieved.

**frame**
A complete image. In interlaced formats, a frame is composed of two fields.

**ft**
Feet.

#### H

**h**
Hour.

**hue**
Represents the dominant color of a pixel. The hue function is a continuous function that covers all the possible colors generated using the R, G, and B primaries. See also RGB.

**Hz**
Hertz. Frequency in units of 1/second.

#### I

**I/O**
Input/output. The transfer of data to/from a computer system involving communications channels, operator interface devices, and/or data acquisition and control interfaces.

**IC**
Integrated circuit.
IEEE

Institute of Electrical and Electronics Engineers.

in.

Inches.

instrument driver

A set of high-level software functions, such as NI-IMAQ, that control specific plug-in computer boards. Instrument drivers are available in several forms, ranging from a function callable from a programming language to a virtual instrument (VI) in LabVIEW.

interlaced

A video frame composed of two interleaved fields. The number of lines in a field are half the number of lines in an interlaced frame.

interrupt

A computer signal indicating that the CPU should suspend its current task to service a designated activity.

interrupt level

The relative priority at which a device can interrupt.

IRQ

Interrupt request. See also interrupt.

K

k

Kilo. The standard metric prefix for 1,000, or $10^3$, used with units of measure such as volts, hertz, and meters.

K

Kilo. The prefix for 1,024, or $2^{10}$, used with B in quantifying data or computer memory.

kbytes/s

A unit for data transfer that means 1,000 or $10^3$ bytes/s.

Kword

1,024 words of memory.

L

line count

The total number of horizontal lines in the picture.

LSB

Least significant bit.

LUT

Lookup table. Table containing values used to transform the gray-level values of an image. For each gray-level value in the image, the corresponding new value is obtained from the lookup table.
**Glossary**

**M**

- **m**: Meters.
- **M**: (1) Mega, the standard metric prefix for 1 million or $10^6$, when used with units of measure such as volts and hertz; (2) mega, the prefix for $1,048,576$, or $2^{20}$, when used with B to quantify data or computer memory.
- **MB**: Megabyte of memory.
- **Mbytes/s**: A unit for data transfer that means 1 million or $10^6$ bytes/s.
- **memory buffer**: See buffer.
- **memory window**: Continuous blocks of memory that can be accessed quickly by changing addresses on the local processor.
- **MSB**: Most significant bit.
- **MTBF**: Mean time between failure.
- **mux**: Multiplexer. A switching device with multiple inputs that selectively connects one of its inputs to its output.

**N**

- **NI-IMAQ**: Driver software for National Instruments image acquisition hardware.
- **noninterlaced**: A video frame where all the lines are scanned sequentially, instead of divided into two frames as in an interlaced video frame.
- **NTSC**: National Television Standards Committee. The committee that developed the color video standard used primarily in North America, which uses 525 lines per frame. See also PAL.
- **NVRAM**: Nonvolatile RAM. RAM that is not erased when a device loses power or is turned off.

**O**

- **operating system**: Base-level software that controls a computer, runs programs, interacts with users, and communicates with installed hardware or peripheral devices.
PAL  Phase Alternation Line. One of the European video color standards; uses 625 lines per frame. See also NTSC.

PCI  Peripheral Component Interconnect. A high-performance expansion bus architecture originally developed by Intel to replace ISA and EISA. PCI offers a theoretical maximum transfer rate of 132 Mbytes/s.

PFI  Programmable function input.

PGIA  Programmable gain instrumentation amplifier.

Pixel  Picture element. The smallest division that makes up the video scan line; for display on a computer monitor, a pixel’s optimum dimension is square (aspect ratio of 1:1, or the width equal to the height).

Pixel clock  Divides the incoming horizontal video line into pixels.

Pixel count  The total number of pixels between two horizontal synchronization signals. The pixel count determines the frequency of the pixel clock.

Protocol  The exact sequence of bits, characters, and control codes used to transfer data between computers and peripherals through a communications channel.

PTS  Points.

PXI  PCI eXtensions for Instrumentation. An open specification that builds on the CompactPCI specification by adding instrumentation-specific features.

RAM  Random-access memory.

Real time  A property of an event or system in which data is processed as it is acquired instead of being accumulated and processed at a later time.

Resolution  The smallest signal increment that can be detected by a measurement system. Resolution can be expressed in bits, in proportions, or in percent of full scale. For example, a system has 12-bit resolution, one part in 4,096 resolution, and 0.0244 percent of full scale.
## Glossary

**RGB**  
Color encoding scheme using red, green, and blue (RGB) color information where each pixel in the color image is encoded using 32 bits: 8 bits for red, 8 bits for green, 8 bits for blue, and 8 bits for the alpha value (unused).

**ribbon cable**  
A flat cable in which the conductors are side by side.

**ROI**  
Region of interest. A hardware-programmable rectangular portion of the acquisition window.

**ROM**  
Read-only memory.

**RTSI bus**  
Real-Time System Integration Bus. The National Instruments timing bus that connects image acquisition and DAQ boards directly, by means of connectors on top of the boards, for precise synchronization of functions.

### S

s  
Seconds.

**scaling down circuitry**  
Circuitry that scales down the resolution of a video signal.

**scatter-gather DMA**  
A type of DMA that allows the DMA controller to reconfigure on-the-fly.

**SDRAM**  
Synchronous dynamic RAM.

**SO-DIMM**  
Small outline dual inline memory module.

**SRAM**  
Static RAM.

**system RAM**  
RAM installed on a personal computer and used by the operating system, as contrasted with onboard RAM.

### T

**tap**  
A stream of pixels from a camera. Some cameras send multiple streams, or taps, of data over a cable simultaneously to increase transfer rate.

**transfer rate**  
The rate, measured in bytes/s, at which data is moved from source to destination after software initialization and set up operations. The maximum rate at which the hardware can operate.

**trigger**  
Any event that causes or starts some form of data capture.
<table>
<thead>
<tr>
<th><strong>trigger control and mapping circuitry</strong></th>
<th>Circuitry that routes, monitors, and drives external and RTSI bus trigger lines. You can configure each of these lines to start or stop acquisition on a rising or falling edge.</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>TTL</strong></td>
<td>Transistor-transistor logic.</td>
</tr>
<tr>
<td><strong>V</strong></td>
<td></td>
</tr>
<tr>
<td><strong>VI</strong></td>
<td>Virtual Instrument. (1) A combination of hardware and/or software elements, typically used with a PC, that has the functionality of a classic stand-alone instrument (2) A LabVIEW software module (VI), which consists of a front panel user interface and a block diagram program.</td>
</tr>
</tbody>
</table>
# Index

## A
- acquisition
  - acquisition window control, 2-5
  - start conditions, 2-5
  - video acquisition, 2-5
- acquisition, scaling, and ROI circuitry, 2-4
- advanced clock generation, 2-3
- application software
  - Vision Builder AI, 1-4
  - Vision Development Module, 1-4

## B
- block diagram of NI 1422, 2-2
- board configuration NVRAM, 2-4
- bus master PCI interface, 2-4

## C
- calibration certificate (NI resources), A-2
- compactPCI, using with PXI, 1-2
- conventions used in the manual, v

## D
- Declaration of Conformity (NI resources), A-1
- diagnostic tools (NI resources), A-1
- differential/TTL converters, 2-2
- documentation
  - conventions used in the manual, v
  - NI resources, A-1
  - drivers (NI resources), A-1

## E
- examples (NI resources), A-1

## H
- help, technical support, A-1
- high-speed timing, 2-4

## I
- I/O connector, 3-1
- instrument drivers (NI resources), A-1
- integration with DAQ and motion control, 1-5

## K
- KnowledgeBase, A-1

## L
- LabVIEW
  - migrating inspection from Vision Builder AI, 1-4
- lookup tables (LUTs), 2-2
- LUTS (lookup tables), 2-2

## M
- motion control, integrating with, 1-5
- multiple-tap data formatter, 2-3

## N
- National Instruments support and services, A-1
- NI 1422
  - block diagram, 2-2
  - functional overview, 2-1
  - hardware overview, 1-3
  - I/O connector signals, 3-3
  - overview, 1-1
  - SCSI pin assignments, 3-2
software programming choices, 1-3
NI support and services, A-1
NI-IMAQ driver software, 1-3

P
programming examples (NI resources), A-1
PXI, using with compactPCI, 1-2

R
RS-232 serial interface, 2-3

S
scatter-gather DMA controllers, 2-4
SCSI pin assignments, 3-2
SDRAM, 2-3
signal connections
  I/O connector, 3-1
software (NI resources), A-1
software programming choices
  NI Vision, 1-4
  NI-IMAQ driver software, 1-3
  Vision Builder AI, 1-4

T
technical support, A-1
training and certification (NI resources), A-1
troubleshooting (NI resources), A-1

V
video acquisition, 2-5
Vision Builder AI
  migrating to LabVIEW, 1-4

W
Web resources, A-1